< 2.11. Pathlines, Streamlines, and Streaklines >

Pathline

- Path through space as a function of time
- Same particle (Lagrangian View)

Streamline

- Parallel to velocity
- Different particles (Eulerian View)

Streakline

- Associated with a particular point P in space which has the fluid moving past it
- Different particle

***** If steady \rightarrow pathline = streamline = streakline





2-D streamline

In 2D

$$vdx - udy = 0$$
$$\frac{dy}{dx} = \frac{v}{u}$$

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< 2.12. Angular velocity, Vorticity, and Strain > Angular velocity: $\vec{\omega} = \frac{1}{2} \nabla \times \vec{V}$

***** Vorticity : $\vec{\xi} = \nabla \times \vec{V} = 2\vec{\omega}$

• Rotational flow : $\vec{\xi} \neq 0$ • Irrotational flow : $\vec{\xi} = 0$

$$\vec{\xi} = \nabla \times \vec{V} = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ u & v & w \end{vmatrix}$$

In 2D

$$\vec{\xi} = (\frac{\partial u}{\partial x} - \frac{\partial u}{\partial y})$$

< 2.13. Circulation >

Strength of Vorticity (Vortex)

$$\Gamma = -\oint_{C} \overrightarrow{V} \cdot \overrightarrow{ds} = -\oint_{S} (\nabla \times \overrightarrow{V}) \cdot \overrightarrow{dS} = -\oint_{S} \overrightarrow{\xi} \cdot \overrightarrow{dS}$$

Stokes Theorem

$$\Gamma = v_{\theta} 2\pi r \Rightarrow v_{\theta} = \frac{\Gamma}{2\pi r}$$

< 2.14. Stream Function >

* In 2D, streamline can be expressed as

u dy - v dx = 0

* Let's define a function which satisfies the above equation, stream function $\psi(x,y) = c$



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< 2.14. Stream Function >



$$d\psi = \frac{\partial \psi}{\partial x} dx + \frac{\partial \psi}{\partial y} dy = 0$$
$$= -v dx + u dy$$

In polar coordinate

$$\begin{split} v_r \! = \! \frac{1}{r} \frac{\partial \psi}{\partial \theta} \\ v_\theta \! = \! - \! \frac{\partial \psi}{\partial r} \end{split}$$

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< 2.15. Velocity Potential > * Vorticity: $\vec{\xi} = \nabla \times \vec{V}$ Irrotational: $\nabla \times \vec{V} = 0$

***** Using vector identity $\nabla \times (\nabla \phi) = 0$

 $\stackrel{
ightarrow}{V}=
abla\phi
ightarrow$: Velocity potential

$$\nabla \times \overrightarrow{V} = \nabla \times (\nabla \phi) = 0$$

< 2.15. Velocity Potential >

 $\begin{array}{l} \stackrel{\rightarrow}{v} = u_i + v_j + w_k = \frac{\partial \phi}{\partial x}i + \frac{\partial \phi}{\partial y}j + \frac{\partial \phi}{\partial z}k \\ u = \frac{\partial \phi}{\partial x}, \; v = \frac{\partial \phi}{\partial y}, \; w = \frac{\partial \phi}{\partial z} \end{array}$

In cylindrical coordinate, $v_r = \frac{\partial \phi}{\partial r}, v_\theta = \frac{1}{r} \frac{\partial \phi}{\partial \theta}, v_z = \frac{\partial \phi}{\partial z}$ In spherical coordinate, $v_r = \frac{\partial \phi}{\partial r}, v_\theta = \frac{1}{r} \frac{\partial \phi}{\partial \theta}, v_\phi = \frac{1}{r sin\theta} \frac{\partial \phi}{\partial \Phi}$

 $\overrightarrow{V} = \nabla \phi$

< 2.15. Velocity Potential >

Velocity potential is differentiated parallel to the velocity whereas the stream function is differentiated normal to the velocity.

$$d\psi = \frac{\partial \psi}{\partial x} dx + \frac{\partial \psi}{\partial y} dy = 0 \quad \Rightarrow \quad \left(\frac{dy}{dx}\right)_{\psi = const} = \frac{v}{u}$$

$$(\frac{\partial \psi}{\partial x})_{\psi = const} = -\frac{u}{v}$$

$$d\phi = \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy = 0 \quad \Rightarrow \quad \left(\frac{dy}{dx}\right)_{\phi = const} = -\frac{u}{v}$$

$$(\frac{\partial \psi}{\partial x})_{\psi = const} \quad \Rightarrow \quad \left(\frac{dy}{dx}\right)_{\phi = const} = -1$$
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< 2.15. Velocity Potential >

- Velocity potential is defined for irrotational flow only whereas the stream function is used for both irrotational & rotational flow.
- Velocity potential applied to 3D, whereas stream function is defined for 2D only.